

# 13. Oszillatoren. 正弦波振荡器.

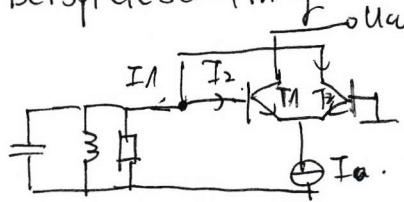
基本原理.

$$设开环放大倍数 K(s) = \frac{U_O(s)}{U_I(s)}, 反馈系数 F(s) = \frac{U'_I(s)}{U_O(s)}, 闭环增益 K_{\text{out}}(s) = \frac{U_O(s)}{U_I(s)}$$

$$U_{Ii}(s) = U_I(s) + U'_I(s) \Rightarrow U_I(s) = U_I^*(s) - U'_I(s)$$

$$K_{\text{out}}(s) = \frac{U_O}{U_I - U'_I(s)} = \frac{U_O/U_I}{1 - \frac{U'_I(s)}{U_O(s)}} = \frac{K(s)}{1 - F(s) \cdot K(s)} \Rightarrow 自激振荡 F(s) \cdot K(s) = 1, 则没有输入 电路也能起振.$$

Beispielschaltung



$$I_1 = -I_2 \Rightarrow I_1 + I_2 = 0 \Rightarrow U_1 = U_2 = 0.$$

$$y_1 = \frac{1}{R} + j\omega C + \frac{1}{j\omega L} \quad y_2 \text{ 由门限值分析 (线性近似) }$$

$$\begin{aligned} I_2 &= \frac{1}{R} + j\omega C \\ &= \frac{1}{R} + j\omega m_2. \end{aligned}$$

$$I_2 = \frac{1}{2} g_m \cdot (-1) = -\frac{U}{2} \cdot g_m \Rightarrow y_2 = -\frac{g_m}{2} = \frac{-I_0}{4U_T} \quad f_c = \frac{1}{2\pi\sqrt{LC}}$$

$$\Rightarrow \frac{1}{R} = \frac{I_0}{4U_T}, \quad I_0 = \frac{4U_T}{R}, \quad j\omega C + \frac{1}{j\omega L} = 0 \Rightarrow -\omega^2 CL + 1 = 0$$

非线性分析. 由路方程

$$I_1 = \frac{U}{R} + \frac{1}{2} \int u dt + C \frac{du}{dt} \quad I_2 = \frac{I_0}{2} (1 - \tanh \frac{u}{2U_T})$$

$$\Rightarrow I_1 + I_2 = 0, \quad \frac{dI_1}{dt} + \frac{dI_2}{dt} = 0 \quad 0 = \frac{1}{R} \frac{du}{dt} + \frac{1}{2} \frac{du}{dt} + C \frac{d^2u}{dt^2} - \frac{I_0}{4U_T} (1 - \tanh \frac{u}{2U_T}) \frac{du}{dt}$$

$$\Rightarrow u + \frac{1}{R} \left[ 1 - \frac{I_0 R}{4U_T} (1 - \tanh^2 \frac{u}{2U_T}) \right] \frac{du}{dt} + LC \frac{d^2u}{dt^2} = 0$$

$$\Rightarrow \frac{d^2u}{dt^2} + \frac{1}{RC} \left[ 1 - \frac{I_0 R}{4U_T} (1 - \tanh^2 \frac{u}{2U_T}) \right] \frac{du}{dt} + \frac{1}{LC} \cdot u = 0$$

产生正弦振荡. ~~由~~  $A \cos \omega t, B \sin \omega t \Rightarrow c_1 e^{j\omega t} + c_2 e^{-j\omega t}$ . 则  $1 - \frac{I_0 R}{4U_T} (1 - \tanh^2 \frac{u}{2U_T}) = 0$

$$\begin{cases} 0 = \tanh^2 \frac{u}{2U_T} \\ 1 = \frac{I_0 R}{4U_T} \end{cases} \Rightarrow \begin{cases} u = 0 \\ I_0 = 4U_T/R \end{cases}$$

$$\Rightarrow u = \hat{u} \sin \omega t, f_1 = \frac{1}{2\pi\sqrt{LC}}$$

非线性分析. 特型振荡 (-P1), N(j\omega), 非线性器件的建模. 由 ~~线性化~~ 公式  $P_1$  为元.

$$I_2 = F(u) = -\frac{I_0}{2} (1 - \tanh \frac{\hat{u} \sin \omega t}{2U_T}), \quad a_1 = 0 \quad b_1 = -\frac{I_0}{2\pi} \int_0^{2\pi} (1 - \tanh \frac{\hat{u} \sin \omega t}{2U_T}) \sin \omega t dt$$

$$\Rightarrow N(j\omega) = \frac{b_1}{a_1}, \quad G(j\omega) = R + j\omega C + j\omega L \Rightarrow \frac{1}{j\omega C} + j\omega L = 0 \Rightarrow f = \frac{1}{2\pi\sqrt{LC}}$$

$$\Rightarrow \frac{b_1}{a_1} \cdot R = 1 \Rightarrow b_1 = \frac{a_1}{R} = \frac{I_0}{2\pi} \int_0^{2\pi} \tanh \frac{\hat{u} \sin \omega t}{2U_T} \sin \omega t dt.$$

$$1 = \frac{I_0 \cdot R}{a_1} \quad \boxed{a_1(\frac{\hat{u}}{2U_T})} = \frac{I_0 \cdot R}{2\pi \cdot 2U_T} \cdot \frac{2U_T}{a_1} \quad \boxed{a_1(\frac{\hat{u}}{2U_T})}$$

$$\rightarrow \frac{x}{y} \cdot \frac{1}{\pi} \int_0^{2\pi} [\tanh(\eta \sin \omega t)] \sin \omega t dt - 1 = 0. \quad \text{其中, } y = \frac{\hat{u}}{2U_T}, \quad x = \frac{I_0 R}{4U_T}.$$

(1) tanh-P1近似:  $\tanh(x) \approx x \Rightarrow \frac{x}{y} \cdot \frac{1}{\pi} \cdot y \cdot \frac{1}{2} \cdot 2\pi - 1 = 0, x = 1, y \text{ 必须很小.}$

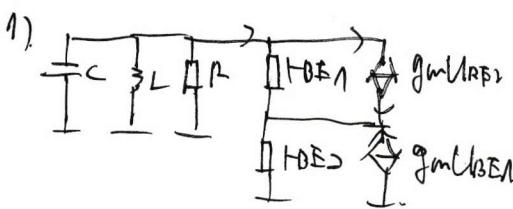
$$(2) \tanh = P1. \quad \tanh(x) \approx x - \frac{x^3}{3} \Rightarrow \frac{x}{y} \cdot \frac{1}{\pi} \int_0^{2\pi} [y \sin^2 \omega t - \frac{y^3 \sin^4 \omega t}{3}] dt = \frac{x}{y} \cdot \frac{1}{\pi} \cdot (y \cdot \pi + y^3 \cdot \frac{3}{4} \cdot \pi) - 1 = 0$$

$$(3) \tanh = P1. \quad \tanh(x) \approx x - \frac{x^3}{3} + \frac{2x^5}{15}, \quad x + x \cdot \frac{3}{4} - \frac{2}{15} \cdot y^4 \cdot \frac{11}{24} - 1 = 0 \Rightarrow x > 1, \quad x < \frac{15}{11}.$$

$$\text{大信号 } \tanh(x) = \pm 1 \Rightarrow \hat{u}_m = \frac{2}{\pi} R I_0 \quad I_0 > \frac{4U_T}{R}, \quad a_1 = 0, \quad I_0 < \frac{64U_T}{13R} = 42.2 \text{ mA} \quad \frac{1}{4} - 12(1 - \frac{1}{x}) > 0 \quad a_1 = 63.4 \text{ mV.}$$

$$\sin^n x = \begin{cases} \frac{(-1)^{m-1}}{2m-1} \frac{1}{2} \frac{1}{2m-1} \dots 2\pi, & n = 2m \\ 0, & n = 2m+1 \end{cases}$$

02-01



$$I = \frac{U}{R} = \frac{\frac{U}{2}}{\frac{1}{2} \cdot \frac{I_0}{2nT}} = \frac{4nT}{I_0}, \quad |P| = |I| \cdot U, \quad I_0 = \frac{4U}{P} = 34.7mA$$

$I_m = 0.67mA$

$$k_7 \quad f_1 = \frac{1}{2\pi\sqrt{L_U}} \Rightarrow C = 2.533 \text{ nF}$$

$$O_2 + O_2 \cdot$$

$$1) \underline{z} = \frac{1}{j\omega C_p + \frac{1}{j\omega L + \frac{1}{j\omega C} + R}} , \text{ capacitor} \quad \underline{z} = j\omega L + \frac{1}{j\omega C} + R. \quad \text{capacitor's impedance}$$

$$f_0 = \frac{1}{2\pi} \frac{1}{\sqrt{L_C}} = 100,32 \text{ kHz}. \quad Q = \frac{W_0 L}{F} = \frac{W_0}{m_0 C} = \frac{L}{A L_C \cdot \gamma} = \frac{1}{F} \cdot \sqrt{\frac{L}{C}} = 100 \text{ rad/s}$$

$$2) \quad U_a = iD \cdot R_D + u_{ref}$$

$$i_D = |U_2 - i_D \cdot R_S| / \pm 19 \mu$$

$$\Rightarrow U_2 = \frac{I_D(gm_s + 1)}{g_m} \quad U_A = U_2 \cdot \frac{\frac{R_D}{gm_s + 1}}{gm_s + 1} + U_{ref.} \Rightarrow V_o = \frac{\frac{R_D}{gm_s + 1}}{gm_s + 1} + \boxed{\frac{U_{ref.}}{U_2}}$$

$$1. \text{ Fall} \quad v_1 = 0.367 \quad 2. \text{ Fall}, \quad v_2 = 2.77$$

$$3) K = \frac{n_2}{n_a} = \frac{P_2}{R_1 + R_2} = \frac{1}{1 + \frac{P_1}{P_2}}$$

$$\cancel{V_2 = \frac{P_1}{g_m}} \quad V_2 + k \geq 1 \quad \frac{P_1}{R_2} + 1 = V_2 \quad \frac{P_1}{R_2} = V_2 - 1 = 1.57.$$

$$4). \quad U_a = \frac{V_2}{\sqrt{1 + \frac{R_1}{R_2}}} \cdot U_a + U_{ref}.$$

$$U_{ref} = I_D \cdot R_S = U_a \frac{R_N}{R_N + R_L} \Rightarrow U_a = I_D \cdot R_S \cdot \left(1 + \frac{R_L}{R_N}\right) = U_a = I_D \cdot R_S \cdot V_N \quad 37+$$

$$U_a - U_{ref} = I_D \cdot R_D \Rightarrow U_{ref} = U_a - I_D \cdot R_D = 5,42 \text{ V}$$

【注】. 先前的输出影响放大倍数。~~且~~ AUGS A 之输出倍数

02-03.

$$11. Y_L = \frac{1}{R} + j\omega C + \frac{1}{j\omega L} \quad f_R = \frac{1}{2\pi\sqrt{LC}} = 1 \text{ MHz} \quad (1000 + 8.754 \text{ Hz})$$

$$2). G(\gamma_{m_1}) = \text{R} . N(\gamma_{m_1}) = \frac{f_{2,1}}{u} = \frac{-T_0}{2\pi m_1} \int_0^{2\pi} \tan r \left( \frac{R}{2m_1} \cdot \sin m_1 t \right) \sin u_1 t dt$$

$$(G(\gamma_{m_1})) \cdot (N(\gamma_{m_1})) = 1.$$

### 3). Ans Vorlesung

$$3.1) \quad I_0 = \frac{4U_T}{B} = 34.7 \text{ mA}$$

$$3.2) \quad \frac{U_0}{U_1} = \sqrt{1 - \frac{4NT}{P_{10}}} = 38 \text{ mV}$$

7.3) pos. Halbwelle.  $T_2$  sperata.  $I_1 + I_2 = C$   
 neg. Halbwelle.  $T_1$  sperata.  $I_2 = I_0$

$$2 \cdot \frac{x}{y} \cdot \frac{1}{2} \int_0^{\pi} \sin x \, dx = 1 > 0 \quad \text{1st quadrant} \quad y_0 \quad y = \frac{4}{\pi} x$$

$$2 \cdot \frac{x}{\eta} - \frac{2}{\pi} - 1 = 0 \quad x = \frac{2 \eta p}{4 \pi n} \quad \eta = \frac{\eta_1}{2 \pi n} \quad \eta_1 = 2 \eta_1 \cdot \frac{2 \pi}{2 \pi n} \cdot \frac{p}{4 \pi n} = \cancel{2 \eta_1} \cdot \frac{2 p}{4 \pi n} = 1 p 1 m V$$

$$\int_0^{2\pi} \sin^n x = \begin{cases} \frac{2m-1}{2m} \cdot \frac{2m-3}{2m-1} \cdot \dots \cdot \frac{1}{2} \cdot 2\pi & n = 2m \\ 0 & n = 2m-1 \end{cases}$$

$$\frac{I_0}{2} \rightarrow 0$$

b<sub>1</sub> + πx<sub>2</sub>.